



# VC-Dimension

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## Roadmap

### last time

- We will start by analyzing finite hypothesis spaces ( $|\mathcal{H}| < \infty$ ) with zero training error ( $R_n(h) = 0$ )  $\Rightarrow$  **Haussler's Theorem**
- We will then generalize to finite hypothesis spaces ( $|\mathcal{H}| < \infty$ ) with non-zero training error ( $R_n(h) > 0$ )  $\Rightarrow$  **General PAC Bounds**

### today

- We will finally discuss infinite hypothesis spaces ( $|\mathcal{H}| = \infty$ )  $\Rightarrow$  **VC-dimension**

## PAC Bounds

Given finite hypothesis space  $\mathcal{H}$ , dataset  $\mathcal{D}$  with  $n$  iid samples, and probability of error on one sample  $> \epsilon$  (where  $0 \leq \epsilon \leq 1$ ), then ...

### Theorem [Haussler '88]

... for any learned hypothesis  $h$  that is consistent with the training data ( $R_n(h) = 0$ ),

$$P(R(h) > \epsilon) \leq |\mathcal{H}|e^{-n\epsilon}$$

### Theorem [Generalization Bound for $|\mathcal{H}|$ Hypotheses]

... for any learned hypothesis  $h$ ,

$$P(R(h) - R_n(h) > \epsilon) \leq |\mathcal{H}|e^{-2n\epsilon^2}$$

Based on slides by Carlos Guestrin and David Sontag

## Limitations of PAC Bound

With probability at least  $1 - \delta$ ,

$$R(h) \leq \underbrace{R_n(h)}_{\text{bias}} + \underbrace{\sqrt{\frac{1}{2n} \left( \ln |\mathcal{H}| + \ln \frac{1}{\delta} \right)}}_{\text{variance}}$$

What happens for infinite hypothesis spaces ( $|\mathcal{H}| = \infty$ ), e.g.  $\mathcal{H} = \{\text{all linear classifiers}\}$ ?

- PAC bound becomes trivial (“infinite” variance)
- We need another way of measuring  $|\mathcal{H}|$

Based on slides by Piyush Rai

# VC-Dimension

## Learning Goals

- Define shattering
- Define VC-dimension

## Vapnik-Chervonenkis (VC) Dimension

### Goal

Measure “complexity” of a particular class of models independently of training set

### Intuition

We only care about the maximum number of points that can be classified correctly

# Example

How many points can a linear boundary classify exactly in 1D?

1 point?

2 points?

3 points?

Based on slides by Carlos Guestrin and David Sontag



# Shattering

## Definition

A set  $S = \{x^{(1)}, \dots, x^{(m)}\}$  of points  $x^{(i)} \in \mathcal{X}$  is **shattered** by hypothesis class  $\mathcal{H}$  if and only if

- for **any set of labels**  $\{y^{(1)}, \dots, y^{(m)}\}$ ,
- there exists some **consistent**  $h \in \mathcal{H}$ ,  
i.e.  $h(x^{(i)}) = y^{(i)}$  for all  $i = 1, \dots, m$ .

(Note that  $S$  has no relation to the training set.)

Based on notes by Andrew Ng

# More Examples

Suppose  $\mathcal{H}$  is the set of linear classifiers in 2D.

Can you find a set of 3 points in 2D that  $\mathcal{H}$  can shatter?

Based on notes by Andrew Ng



## A Note

There may exist a set of 3 points in 2D that  $\mathcal{H}$  cannot shatter.



No consistent linear classifier exists for this labeling.

We only care that there exists *at least one* set of 3 points that  $\mathcal{H}$  can shatter.

- **Rule of thumb:** Pick points with maximum separability (e.g. equally spaced along circle).

Continuing our example... Can you find a set of 4 points that  $\mathcal{H}$  can shatter?  
Prove or disprove.

Based on notes by Andrew Ng and example by Eric Eaton



# VC-Dimension and Shattering

We use the concept of shattering to define VC-dimension.

To show that hypothesis class  $\mathcal{H}$  has VC-dimension  $d$  in input space  $\mathcal{X}$ , consider this adversarial “shattering game”:

- We choose  $d$  points in  $\mathcal{X}$  positioned however we want
- Adversary labels these  $d$  points
- We choose a hypothesis  $h \in \mathcal{H}$  that separates the points

The VC-dimension of  $\mathcal{H}$  in  $\mathcal{X}$  is the maximum  $d$  we can choose so that we always succeed.

## Formal Definition

Given hypothesis class  $\mathcal{H}$  and input space  $\mathcal{X}$ , the **Vapnik-Chervonenkis dimension**  $VC(\mathcal{H})$  over input  $\mathcal{X}$  is the size of the largest set of points in  $\mathcal{X}$  that is shattered by  $\mathcal{H}$ .

- If  $\mathcal{H}$  can shatter arbitrarily large sets, then  $VC(\mathcal{H}) = \infty$ .

Based on notes by Andrew Ng and slides by Piyush Rai

# VC-Dimension of Linear Classifiers

For hyperplane with bias, we (informally) showed that...

- VC-dim in  $\mathbb{R}^1 = 2$
- VC-dim in  $\mathbb{R}^2 = 3$
- VC-dim in  $\mathbb{R}^d$ ?

Recall that such a classifier in  $\mathbb{R}^d$  is defined by  $d+1$  parameters (one per feature + bias term)

- for linear classifiers, high  $d \Rightarrow$  high complexity
- rule of thumb:

Based on slides by Piyush Rai



# More VC-Dimension Examples

What is the VC-dimension of 1NN?

What is the VC-dimension of a SVM with RBF kernel?

Based on examples by Piyush Rai [Image from Chris Burges]



## Using VC-Dimension in Generalization Bounds

Recall PAC-based generalization bound for hypothesis class  $\mathcal{H}$ :

$$R(h) \leq R_n(h) + \sqrt{\frac{1}{2n} \left( \ln |\mathcal{H}| + \ln \frac{1}{\delta} \right)}$$

If  $|\mathcal{H}| = \infty$  but  $\text{VC}(\mathcal{H}) = d$  in  $\mathcal{X}$ ,

$$R(h) \leq R_n(h) + \sqrt{\frac{1}{2n} \left[ d \left( \ln \frac{2n}{d} + 1 \right) + \ln \frac{4}{\delta} \right]}$$

where

$n$  = training set size

$d$  = VC-dimension of hypothesis class

$\delta$  = probability that bound fails

For linear SVM, what does this bound imply?

Note same bias/variance trade-off as always!

Based on slides by Piyush Rai



# VC-Dimension of SVMs

But for RBF SVM,  $VC(\mathcal{H}) = \infty$ . Is this bad?

- Not really. SVM's large margin property ensures good generalization.

**Theorem (Vapnik 1982): Generalization Bound for SVM**

- Given  $n$  data points  $X = \{x^{(i)}\}_{i=1}^n$  such that for all  $i$ ,  $x^{(i)} \in \mathbb{R}^d$  and  $\|x^{(i)}\| < R$ .
- Define  $\mathcal{H}_\gamma$  to be the set of classifiers in  $\mathbb{R}^d$  with margin  $\gamma$  on  $X$ .

Then  $VC(\mathcal{H}_\gamma)$  is bounded by

$$VC(\mathcal{H}_\gamma) \leq \min \left\{ d, \left\lceil \frac{4R^2}{\gamma^2} \right\rceil \right\}$$

And with probability  $1 - \delta$ ,

$$R(h) \leq R_n(h) + \sqrt{\frac{1}{2n} \left[ VC(\mathcal{H}_\gamma) \left( \ln \frac{2n}{VC(\mathcal{H}_\gamma)} + 1 \right) + \ln \frac{4}{\delta} \right]}$$

Note: large  $\gamma \Rightarrow$  small VC-dim  $\Rightarrow$  low complexity of  $\mathcal{H}_\gamma \Rightarrow$  good generalization

Based on slides by Piyush Rai

# Learning Theory Take-Aways

- Care about generalization error, not training error
- Standard PAC bounds only apply to finite hypothesis classes
- VC-dimension is measure of complexity of infinite-sized hypothesis classes
- We have formalized the following intuition: suppose we find a model with low training error (low bias)
  - if  $|\mathcal{H}|$  large (relative to size of training data), then most likely got lucky (high variance)
  - if  $|\mathcal{H}|$  sufficiently constrained and / or large training set, then low training error likely to be evidence of low generalization error (low variance)
- All of this theory is for binary classification
  - $\Rightarrow$  it can be generalized to multi-class and regression

Based on slides by Piyush Rai and Eric Eaton